

Control Charts with Robust Probability Limits

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ABSTRACT Two of the main problems in constructing a control chart for detecting shifts in process variation are to estimate the process variation based on preliminary samples taken from the process and to evaluate its control limits. The unknown process variation is generally estimated from either the sample standard deviations or ranges of the preliminary samples. These classical estimates of process variation are highly sensitive to the presence of contaminated data in the preliminary samples and subsequently reduce the power of control charts in detecting assignable causes. The 3-sigma control limits of the Shewhart control charts are evaluated based on the assumption that the sample statistic being plotted is Gaussian distributed. However, the sampling distributions of the sample standard deviation and range are skewed even if the samples are taken from a Gaussian population. The aims of this paper are (i) to discuss robust estimates of scale parameter from preliminary samples taken from the process under study, and (ii) to construct control charts with probability limits evaluated using robust estimators that are resistance to contaminated preliminary samples.

ABSTRAK Dua masalah utama dalam pembinaan carta kawalan bagi mengesan perubahan dalam serakan proses adalah menganggar serakan proses berasaskan sampel awalan yang diambil dari proses, dan menentukan had kawalannya. Lazimnya, serakan proses yang tidak diketahui diukur dengan sisihan piawai atau julat sampel awalan. Penganggar klasik bagi serakan proses adalah sangat sensitif kepada kewujudan data tercemar dalam sampel awalan, dan seterusnya mengurangkan kuasa carta kawalan dalam mengesan penyebab umpukan. Carta kawalan 3-sigma untuk carta kawalan Shewhart ditentukan berdasarkan andaian bahawa sampel statistik yang dikaji adalah bertaburan Gaussian. Bagaimanapun, taburan pensampelan bagi sisihan piawai sampel dan julat sampel adalah pencong walaupun sampel dipilih dari populasi Gaussian. Tujuan kertas ini adalah (i) membincang penganggar kukuh bagi parameter skel dari sampel awalan yang diambil dari proses dikaji, dan (ii) membina carta kawalan dengan had kebarangkalian yang dinilai dengan menggunakan penganggar kukuh yang mempunyai rintangan terhadap sampel awalan tercemar.

(Robust estimator, robust control chart, asymmetric control limits)

INTRODUCTION

Control chart is a basic tool in statistical process control for detecting shifts in process mean and variation. The standard Shewhart control charts are constructed under the normality assumption. Let w be a sample statistic that measures a quality characteristic of interest in the process under study, and let that the mean of w be μ_w and the standard deviation of w be σ_w . Then the center line, the upper and lower control limits of the

standard Shewhart control chart for the sample statistic w are given as

$$UCL_w = \mu_w + L\sigma_w$$

$$CL_w = \mu_w$$

$$LCL_w = \mu_w - L\sigma_w$$

where the factor L is usually taken to be 3.0 irrespective of the distribution of w . However, the sampling distributions of the sample range and sample standard deviation are fairly skewed, even

for samples taken from a Gaussian distribution, thus the control limits of the R -chart and s -chart set at plus and minus L standard deviations of its mean value are inappropriate. It has been pointed out that for highly skewed process, samples of size four or five are not sufficient to satisfy the normality assumption of the sample mean [1]. The study in [2] also concluded that the false alarm rate of out-of-control signals would be greatly increased if the normality assumption of the sample mean is violated. To avoid this drawback, one should construct the Shewhart charts using the asymmetric probability limits instead of the 3-sigma control limits. The construction of s and R charts with asymmetric probability limits, evaluated based on additional knowledge on the distribution of the process under study, are available and can be found in [3, 4, 5].

Another problem of the Shewhart control charts that have attracted a lot of attention lately is on the estimation of the unknown process mean μ and standard deviation σ . In most applications, the location and scale parameters are estimated from preliminary subgroups taken from the process under study when it is operating in the state of statistical control with only chance causes of variation present. The most widely used estimator of the location parameter is the average of the m sample means evaluated from the m preliminary subgroups. The scale parameter is usually estimated based on the average of the m sample ranges, the average of the m sample standard deviations or the square of the average of the m sample variances. However, these classical unbiased estimates of location and scale parameters are greatly affected by the presence of contaminated and outlying data in the preliminary samples. An inflated estimate of σ would result in wider control limits and subsequently reduces the power of control chart in detecting out-of-control signals. A deflated estimate of σ would result in shorter control limits that lead to higher false alarm rate of detecting assignable causes. To avoid this drawback, an alternative is to construct a control chart based on a sample statistic (e.g. sample mean, standard deviation or range) that is sensitive to out-of-control signal, however, with its control limits evaluated using robust estimators that are resistant to contaminated sample data. A good robust estimator is efficient and resistant. High efficiency implies that the sampling distribution of the estimator has small variance even when we

are sampling from a non-normal distribution. An estimator is resistant if small changes in some of the sample data or large changes in a few of the data values have a small effect on its estimate value.

The aims of this paper are (i) to discuss robust estimates of scale parameter from preliminary samples taken from the process under study, and (ii) to construct control charts with probability limits evaluated using robust estimators that are resistance to contaminated preliminary samples. The construction of s , R and \bar{x} charts with probability limits evaluated from samples taken from the Gaussian and selected non-Gaussian populations are discussed in Section 2. Some well develop robust scale estimators for the Gaussian and exponential distributions, as well as a resistant biweight estimator that can be used to estimate the scale parameter of a family of location-scale populations are discussed in Section 3. Our simulation study reveals that control charts with resistant probability limits outperform that constructed with the classical non-resistant scale estimator when the preliminary samples are contaminated. To avoid lengthy discussions, we only report the performance of the s -chart with robust probability limits in Section 4.

SHEWHART CONTROL CHARTS WITH PROBABILITY LIMITS

For a process with known scale parameter σ , the center line and $(1 - \alpha)100\%$ probability limits of the s -chart for samples of size n are defined as

$$UCL_s = B_{1-\alpha/2;n} \sigma$$

$$CL_s = c_n \sigma$$

$$LCL_s = B_{\alpha/2;n} \sigma$$

and that of the R -chart are given as

$$UCL_R = D_{1-\alpha/2;n} \sigma$$

$$CL_R = d_n \sigma$$

$$LCL_R = D_{\alpha/2;n} \sigma$$

where $B_{p;n}$ is the p th percentage point of $V = s/\sigma$ and $c_n = E(V)$; $D_{p;n}$ is the p th percentage point of the relative sample range $U = R/\sigma$ and $d_n = E(U)$.

For samples taken from the exponential, Laplace or logistic distributions, the values of $B_{.00135;n}$, $B_{.99865;n}$ and c_n are given in [4], whereas the values of $D_{.00135;n}$, $D_{.99865;n}$ and d_n are given in [5] for selected sample size n . For the case when samples are taken from the Gaussian distribution, the selected percentage points of R/σ can be obtained from the tables given in [6], whereas the $(\alpha/2)$ th and $(1-\alpha/2)$ th percentage points of s/σ are

$$B_{\alpha/2;n} = \sqrt{\chi_{\alpha/2;n-1}^2 / (n-1)}$$

and

$$B_{1-\alpha/2;n} = \sqrt{\chi_{1-\alpha/2;n-1}^2 / (n-1)}$$

respectively. These values of B 's and D 's are larger than the corresponding factor values of the classical s and R charts constructed with 3-sigma control limits under the normality assumption. A salient feature of these two control charts is that its lower probability limits LCL_s and LCL_R are positive even for sample of size two to five.

For a process with known mean μ and variance σ^2 , the center line and probability limits of the \bar{x} -chart for samples of size n are given as

$$UCL_{\bar{x}} = \mu + L_{1-\alpha/2;n}(\sigma/\sqrt{n})$$

$$CL_{\bar{x}} = \mu$$

$$LCL_{\bar{x}} = \mu - L_{\alpha/2;n}(\sigma/\sqrt{n})$$

where $L_{1-\alpha/2;n}$ and $L_{\alpha/2;n}$ are control factors that depend on the sampling distribution of the sample mean and a specified false alarm rate of α . For samples taken from the Gaussian $N(\mu, \sigma^2)$ distribution, the values of $L_{1-\alpha/2;n}$ and $L_{\alpha/2;n}$ corresponding to $\alpha = 0.0027$ are both taken to be 3.0 irrespective of the value of n . For samples taken from the Laplace(θ, β) distribution with mean $\mu = \theta$ and $\sigma = \sqrt{2}\beta$, the control factors $L_{p;n}$ are taken to be the p th percentage point of the sampling distribution of its sample mean which is distributed as the difference of two IID gamma random variables with shape parameter n and scale parameter β/n . For sample taken from the Gamma(β, ν) distribution with mean $\mu = \nu\beta$ and standard deviation $\sigma = \beta\sqrt{\nu}$, the control factors are given in [7] as $L_{1-\alpha/2;n} = (G_{1-\alpha/2}/\sqrt{n\nu}) - \sqrt{n\nu}$ and $L_{\alpha/2;n} = \sqrt{n\nu} - (G_{\alpha/2}/\sqrt{n\nu})$ where G_p is the p th percentage point of a gamma distribution with shape parameter $n\nu$ and scale parameter equal to 1. The values of $L_{1-\alpha/2;n}$ and $L_{\alpha/2;n}$ for sample of size n taken from the Laplace and exponential distributions are given in Table 1 for $n = 2(1)20$ and 50. Examination of Table 1 reveals that for samples of size as large as 50 taken from the Laplace or the exponential distributions, the values of $L_{1-\alpha/2;n}$ and $L_{\alpha/2;n}$ are not close to its corresponding value of 3.0 as expected under the normality assumption.

Table 1. Factors for constructing the 99.73% probability limits of the \bar{x} chart for samples of size n taken from the Laplace distribution or exponential distribution

n	LAPLACE DISTRIBUTION	EXPONENTIAL DISTRIBUTION		n	LAPLACE DISTRIBUTION	EXPONENTIAL DISTRIBUTION	
	$L_{.00135;n} = L_{.99865;n}$	$L_{.00135;n}$	$L_{.99865;n}$		$L_{.00135;n} = L_{.99865;n}$	$L_{.00135;n}$	$L_{.99865;n}$
2	3.7347	1.1494	5.1067	12	3.1685	2.1584	3.8720
3	3.5422	1.4217	4.7317	13	3.1567	2.1902	3.8378
4	3.4322	1.6034	4.5042	14	3.1465	2.2185	3.8074
5	3.3603	1.7348	4.3476	15	3.1375	2.2440	3.7800
6	3.3094	1.8325	4.2313	16	3.1295	2.2672	3.7552
7	3.2713	1.9150	4.1407	17	3.1224	2.2883	3.7326
8	3.2417	1.9804	4.0674	18	3.1161	2.3078	3.7119
9	3.2179	2.0353	4.0066	19	3.1104	2.3257	3.6929
10	3.1985	2.0822	3.9551	20	3.1052	2.3423	3.6754
11	3.1823	2.1228	3.9107	50	3.0437	2.5802	3.4266

SOME ROBUST AND RESISTANT SCALE ESTIMATORS

It is well established that a robust estimator is able to perform well for its intended purpose even if the underlying assumptions on which it is based are violated [8]. A robust estimator is resistance if it is affected to only a limited extent by the presence of contaminated data or outlying observations. Ideally outlying observations should first be identified using formal hypothesis testing procedures [9] or graphical procedures [10]. However, the outlier detection procedures are in general incapable of detecting small changes in contaminated sample. Therefore in the event that the process standard deviation σ is not available when constructing a control chart, one should estimate the unknown σ by using resistant scale estimators that are able to accommodate and reduce the influence of contaminated data and outlying observations.

There are many robust estimators of location and scale parameters. Some of the widely used robust location estimators are the median, trimmed mean and M -estimator. An efficient median estimator defined as the weighted sum of ordered sample data with symmetric weights has also been discussed [11]. In this paper, we shall focus on the effect of the resistant scale parameter on the performance of the control charts. Three of the commonly used robust scale estimators are the median absolute deviation about the median (MAD) [12], the S_n and Q estimators [13]. For sample of size n , these estimators are defined as

$$MAD = b_n Med_i(|x_i - Med_j x_j|, i, j = 1, 2, \dots, n)$$

$$S_n = s_n Med_i\{Med_j(|x_i - x_j|), i \neq j; i, j = 1, 2, \dots, n\}$$

$$Q = q_n (|x_i - x_j|; i < j; i, j = 1, 2, \dots, n)_k$$

where $()_k$ is the k -th order statistic of the interpoint distances $|x_i - x_j|$ with $k = C_2^n / 4$.

The constants b_n , s_n and q_n are correction factors chosen to ensure that the respective estimator is unbiased to the scale parameter σ . For large Gaussian sample, these correction factors are taken to be $b_n = 1.4826$, $s_n = 1.1926$ and $q_n = 2.2219$ [13]. For large exponential sample, they are taken to be $s_n = 1.6982$ and $q_n = 3.476$ [14]. For finite Gaussian sample of size n , approximate values of these correction factors are also available in [14]. These three estimators have the highest possible breakdown point of 50%, i.e. the estimate of the scale parameter σ remains bounded when fewer than 50% of the data points are replaced by arbitrary values. In contrast, the commonly used sample range and sample standard deviation have breakdown point of 0%.

In constructing control charts, a common approach is to estimate the process variability based on preliminary samples taken during a trial period when the process is operating under the state of statistical control. A robust scale estimator that estimates the process standard deviation based on m preliminary Gaussian

samples was proposed in [15] using the biweight A -estimator [16]. Let $Med_i(x_{k,i})$ and IQR_k be the median and interquartile range of the k th sample with n data $x_{k,1}, x_{k,2}, \dots, x_{k,n}$, the scale estimator in [15] is defined as

$$S_c^* = \frac{N}{(N-1)^{1/2}} \frac{\left[\sum_k \sum_{i:|u_{k,i}| < 1} y_{k,i}^2 (1-u_{k,i}^2)^4 \right]^{1/2}}{\sum_k \sum_{i:|u_{k,i}| < 1} (1-u_{k,i}^2)(1-5u_{k,i}^2)} \quad (1)$$

where $N = mn$ when n is even, $N = m(n-1)$ when n is odd, $u_{k,i} = h_k y_{k,i} / cMAD_N$ in which c is a constant that lies in the range 6 to 12, MAD_N is the MAD of the N median-centered subsample values $y_{k,i} = x_{k,i} - Med_i(x_{k,i})$, and

$$h_k = \begin{cases} 1, & E_k \leq 4.5 \\ E_k - 4.5, & 4.5 < E_k \leq 7.5 \\ c, & E_k > 7.5 \end{cases} \quad (2)$$

with $E_k = IQR_k / MAD_N$. Note that for Gaussian samples with large sample size, we have $E(MAD) \approx \frac{2}{3}\sigma$, thus an estimator S_c^* with $c = 9$ implies that observations with magnitude more than $\frac{2}{3}(9) = 6$ standard deviations away from the median will not be included in the sum of equation (1). The process standard deviation σ is then estimated as

$$S_c = S_c^* / d_{n,m,c} \quad (3)$$

where $d_{n,m,c}$ is a correction factor chosen to ensure that $E(S_c) = \sigma$. The cutoff values of E_k in equation (2) were determined under the normality assumption by the authors via simulation studies. The values of $d_{n,m,c}$ are given in Table 2 for $c = 7$ and selected values of n and m .

A drawback of the estimator S_c is that in computing $u_{k,i}$, the constant c and the cutoff values of E_k cannot be determined analytically under the hypothesized distribution. To overcome this drawback, we propose an alternative

estimator, denoted S_{box}^* , defined as in (1) but with its relative deviation $u_{k,i}$ replaced by

$$u_{k,i} = \begin{cases} \frac{Med_i(x_{k,i}) - x_{k,i}}{Med_i(x_{k,i}) - LF_k}, & x_{k,i} \leq Med_i(x_{k,i}) \\ \frac{x_{k,i} - Med_i(x_{k,i})}{UF_k - Med_i(x_{k,i})}, & x_{k,i} > Med_i(x_{k,i}) \end{cases}$$

where $LF_k = x_{l,n} - k_l(x_{u,n} - x_{l,n})$ and $UF_k = x_{u,n} + k_u(x_{u,n} - x_{l,n})$ in which $x_{l,n}$ and $x_{u,n}$ are the lower-fourth and upper-fourth of the k th sample of size n . The values of k_l, k_u are determined based on the requirement that for an outlier-free random sample taken from the hypothesized distribution, the probability that one or more observations in the sample will be wrongly classified as outliers is equal to a prescribed small value α_0 [10]. The values of $k_l = k_u (=k)$ for sample taken from the standard Gaussian distribution are given in Table 2 for $\alpha_0 = 0.01, 0.05$ and selected sample size n . The process standard deviation σ is then estimated as

$$S_{box} = S_{box}^* / s_{n,m,\alpha_0} \quad (4)$$

where s_{n,m,α_0} is a correction factor chosen to ensure that $E(S_{box}) = \sigma$. The values of s_{n,m,α_0} are given in Table 2 for $\alpha_0 = 0.01$ and 0.05 , and selected values of n and m .

A salient feature of the estimator S_{box} is that in computing $u_{k,i}$, the required values of k_l and k_u can be evaluated explicitly not only for the Gaussian distribution but also for the family of location-scale distributions. For example, the proposed estimator S_{box} can be used to estimate the scale parameter of the asymmetric Laplace, logistic distributions and the asymmetric exponential, extreme-value distributions. For Gaussian and exponential samples of size 9 to 500, the values of k_l and k_u is given in [10].

Table 2. The correction factors $d_{n,m,c}$ of the estimator S_c with $c=7$, the values of $k_1 = k_u (=k)$ and correction factors s_{n,m,α_0} of the estimator S_{box} for m preliminary samples of size n taken from the $N(0,1)$ distribution. Note that α_0 is the error rate that one or more observations in an outlier-free sample would be wrongly classified as outlier(s). The values of $d_{n,m,c}$ and s_{n,m,α_0} are obtained from 100,000 replications of m preliminary samples generated from the $N(0,1)$ distribution

SAMPLE SIZE, n	Mod ($n,4$)	$\alpha_0 = 0.05$						$\alpha_0 = 0.01$						$c = 7.0$	
		S_{n,m,α_0}			S_{n,m,α_0}			S_{n,m,α_0}			S_{n,m,α_0}			$d_{n,m,c}$	
		k	$m=50$	$m=100$	$m=200$	k	$m=50$	$m=100$	$m=200$	k	$m=50$	$m=100$	$m=200$	$m=50$	$m=100$
9	1	3.383	0.94740	0.94751	0.94749	5.783	0.92180	0.92174	0.92162	0.90623	0.90595	0.90578			
13		2.870	0.98677	0.98674	0.98676	4.349	0.95519	0.95504	0.95008	0.94450	0.94417	0.94405			
17		2.650	1.00799	1.00797	1.00806	3.772	0.97422	0.97410	0.97412	0.96423	0.96397	0.96393			
21		2.531	1.02113	1.02120	1.02122	3.464	0.98668	0.98666	0.98664	0.97622	0.97608	0.97602			
25		2.458	1.02997	1.03002	1.03002	3.275	0.99549	0.99547	0.99546	0.98434	0.98419	0.98412			
10	2	2.563	1.01141	1.01156	1.01153	4.104	0.97861	0.97858	0.97847	0.96569	0.96550	0.96530			
14		2.424	1.03098	1.03100	1.03106	3.560	0.99557	0.99545	0.99546	0.98389	0.98365	0.98355			
18		2.351	1.04172	1.04173	1.04181	3.286	1.00556	1.00550	1.00553	0.99399	0.99377	0.99375			
22		2.309	1.04831	1.04833	1.04839	3.123	1.01230	1.01225	1.01226	1.00029	1.00014	1.00009			
26		2.282	1.05264	1.05270	1.05270	3.015	1.01706	1.01707	1.01704	1.00450	1.00439	1.00431			
11	3	2.091	0.98268	0.98280	0.98275	3.209	0.94656	0.94653	0.94644	0.93139	0.93119	0.93104			
15		2.114	1.00702	1.00695	1.00699	3.036	0.97026	0.97011	0.97010	0.95625	0.95596	0.95587			
19		2.124	1.03970	1.02112	1.02118	2.926	0.98457	0.98450	0.98451	0.97097	0.97078	0.97073			
23		2.130	1.03029	1.03040	1.03043	2.852	0.99429	0.99430	0.99430	0.98063	0.98052	0.98046			
27		2.135	1.03674	1.03681	1.03680	2.800	1.00136	1.00137	1.00133	0.98743	0.98735	0.98724			
12	0	2.266	1.08395	1.08413	1.08428	3.355	1.01936	1.01941	1.01945	0.97534	0.97507	0.97494			
16		2.254	1.08362	1.08379	1.08389	3.169	1.02552	1.02557	1.02558	0.98945	0.98925	0.98915			
20		2.239	1.08293	1.08303	1.08314	3.040	1.02958	1.02957	1.02961	0.99748	0.99727	0.99723			
24		2.231	1.08168	1.08181	1.08185	2.956	1.03207	1.03211	1.03209	1.00259	1.00245	1.00238			
28		2.226	1.08040	1.08054	1.08055	2.895	1.03381	1.03388	1.03386	1.00610	1.00602	1.00594			

PERFORMANCES OF THE ROBUST SCALE ESTIMATORS

We shall now examine the performance of the robust scale estimators on preliminary samples taken from the following types of contaminated Gaussian distributions.

Type 1: $CN(p,a)$ distribution

Each of the sample data has $100(1-p)\%$ probability of being drawn from the $N(0,1)$ distribution and $100p\%$ probability of being drawn from the $N(0,a^2)$ distribution with $a \geq 1$.

Type 2: $CSlash(p)$ distribution

Each of the sample data has $100(1-p)\%$ probability of being drawn from a $N(0,1)$ distribution and $100p\%$ probability of being drawn from the long tailed Slash distribution, defined as the $N(0,1)$ random variable divided by an independent uniform random variable on the interval $(0,1)$.

Type 3: $C\chi^2(p,c)$ distribution

Each of the sample data is drawn from the $N(0,1)$ distribution and has a $100p\%$ probability of adding to it a value cV , where V is drawn from the chi-square distribution with one degree of freedom and c is a positive constant value. Note that $c=0$ corresponds to the uncontaminated samples.

The $CN(p,a)$ distribution has tails heavier than that of the standard Gaussian distribution, whereas the $CSlash(p)$ distribution has heavy tails similarly to that of the Cauchy distribution. The $C\chi^2(p,c)$ is a standard Gaussian distribution contaminated by a chi-square distribution with a long right tail. Tables 3 and 4

give the average values of \bar{s}/c_4 , Q , S_c , S_{box} , S_n and MAD evaluated based on 100,000 replications of m samples of size n taken from the uncontaminated $N(0,1)$ distribution, and the abovementioned contaminated Gaussian distributions. The values in bold and italic are the mean absolute deviation between the estimates of the scale parameter σ and its hypothesized value $\sigma = 1$.

Examination of Table 3 reveals that, based on $m = 200$ preliminary samples, the non-robust estimator \bar{s}/c_4 of σ used in constructing the control charts is more sensitive to heavy-tailed distributions than are the robust estimators. For example, for samples of size $n = 20$, the average value of \bar{s}/c_4 is 1.3340 for the $C\chi^2(p,c)$ distribution and 5.6148 for the $CSlash(p)$ distribution when $p = 0.05$ and $c = 3.0$, whereas the respective average values of S_{box} are 1.0231 and 1.0221. Table 3 also reveals that the robust estimators, in particular the S_c and S_{box} estimators, have the smallest mean absolute deviation values (in bold, italic and underlined) amongst the estimators considered for samples of size $n = 10$ and $n = 20$ taken from the contaminated $CN(p,a)$, $C\chi^2(p,c)$ and $CSlash(p)$ distributions with $p = 0.02, 0.05$ and 0.10 , and $a = c = 3$. Table 4 shows that S_{box} remains the most efficient and resistant scale estimator when the number of samples (of size $n = 20$) used in estimating the process standard deviation reduce to $m = 50$. These two tables also indicate that, as expected, \bar{s}/c_4 has the smallest mean absolute deviation when the preliminary samples are uncontaminated Gaussian samples.

Table 3. Comparison of scale estimators for samples taken from uncontaminated or contaminated $N(0,1)$ distributions. The entries are the average values obtained from 100,000 replications of $m=200$ preliminary samples, each of size n , generated from each of the distributions. The value in bold and italic are the mean absolute deviation between the estimates of the scale parameter and its expected value $\sigma = 1$. The underlined values are the smallest mean absolute deviation amongst the estimators considered

p	SCALE ESTIMA-TOR	SAMPLE SIZE $n=10$ DISTRIBUTION, $a=3.0$				SAMPLE SIZE $n=20$ DISTRIBUTION, $a=3.0$			
		$N(0,1)$	$CN(p,a)$	$C\chi^2(p,a)$	$CSlash(p)$	$N(0,1)$	$CN(p,a)$	$C\chi^2(p,a)$	$CSlash(p)$
0.02	sbar/c ₄	1.00004	1.05996	1.11539	1.88546	1.00014	1.06571	1.13833	2.07607
		<u>0.01348</u>	0.05999	0.11539	0.88546	<u>0.00925</u>	0.06571	0.13833	1.07606
	Q	1.00765	1.03503	1.03149	1.02831	1.00052	1.02547	1.02202	1.01924
		0.01804	0.03617	0.03312	0.03040	0.01117	0.02594	0.02287	0.02051
	S _c	1.00004	1.01841	1.01448	1.01566	1.00010	1.01727	1.01121	1.01069
		0.01502	0.02237	0.02077	0.02220	0.01005	0.01842	0.01400	0.01367
	S _{box}	1.00006	1.02096	1.01384	1.01255	1.00012	1.01368	1.00872	1.00857
		0.01518	0.02416	0.01968	0.01880	0.01140	0.01652	0.01370	0.01362
	S _n	0.99303	1.01507	1.01169	1.00955	0.99806	1.01858	1.01531	1.01332
		0.01956	0.02303	0.02165	0.02070	0.01259	0.02057	0.01829	0.01703
MAD	1.00006	1.01866	1.01543	1.01384	1.00013	1.01682	1.01395	1.01252	
	0.02082	0.02630	0.02473	0.02393	0.01475	0.02062	0.01895	0.01818	
0.05	sbar/c ₄	1.00004	1.14734	1.28190	3.08679	1.00014	1.16014	1.33401	5.61484
		<u>0.01348</u>	0.14734	0.28190	2.08681	<u>0.00925</u>	0.16013	0.33401	4.61482
	Q	1.00765	1.07788	1.06875	1.06077	1.00052	1.06456	1.05532	1.04847
		0.01804	0.07789	0.06877	0.06085	0.01117	0.06455	0.05532	0.04847
	S _c	1.00004	1.04822	1.03846	1.03919	1.00010	1.04516	1.02924	1.02751
		0.01502	0.04843	0.03950	0.04054	0.01005	0.04516	0.02939	0.02772
	S _{box}	1.00006	1.05515	1.03858	1.03259	1.00012	1.03593	1.02306	1.02215
		0.01518	0.05523	0.03928	0.03365	0.01140	0.03603	0.02390	0.02310
	S _n	0.99303	1.04966	1.04107	1.03529	0.99806	1.05086	1.04216	1.03719
		0.01956	0.05015	0.04220	0.03711	0.01259	0.05087	0.04223	0.03735
MAD	1.00006	1.04813	1.04043	1.03551	1.00013	1.04318	1.03576	1.03191	
	0.02082	0.04904	0.04212	0.03795	0.01475	0.04334	0.03623	0.03268	
0.10	sbar/c ₄	1.00004	1.28654	1.54269	4.98220	1.00014	1.30772	1.63318	6.65260
		<u>0.01348</u>	0.28654	0.54270	3.98218	<u>0.00925</u>	0.30771	0.63318	5.65257
	Q	1.00765	1.15357	1.13422	1.11765	1.00052	1.13360	1.11364	1.09969
		0.01804	0.15356	0.13422	0.11765	0.01117	0.13360	0.11363	0.09969
	S _c	1.00004	1.10417	1.08377	1.08268	1.00010	1.09745	1.06319	1.05788
		0.01502	0.10417	0.08379	0.08271	0.01005	0.09745	0.06320	0.05787
	S _{box}	1.00006	1.12024	1.09418	1.07018	1.00012	1.07814	1.05111	1.04671
		0.01518	0.12026	0.09418	0.07020	0.01140	0.07814	0.05112	0.04672
	S _n	0.99303	1.11126	1.09276	1.08045	0.99806	1.10837	1.08959	1.07906
		0.01956	0.11126	0.09277	0.08047	0.01259	0.10838	0.08959	0.07907
MAD	1.00006	1.10134	1.08619	1.07369	1.00013	1.09030	1.07537	1.06596	
	0.02082	0.10134	0.08622	0.07377	0.01475	0.09030	0.07538	0.06596	

Table 4. Comparison of scale estimators for samples taken from uncontaminated or contaminated $N(0,1)$ distributions. The entries are the average values obtained from 100,000 replications of m preliminary samples, each of size $n=20$, generated from each of the distributions. The value in bold and italic are the mean absolute deviation between the estimates of the scale parameter and its expected value $\sigma = 1$. The underlined values are the smallest mean absolute deviation amongst the estimators considered

M	SCALE ESTIMATOR	SAMPLE SIZE $n=20$ DISTRIBUTION, $p=0.05, a=3.0$				SAMPLE SIZE $n=20$ DISTRIBUTION, $p=0.10, a=3.0$			
		$N(0,1)$	$CN(p,a)$	$C\chi^2(p,a)$	$C\text{Slash}(p)$	$N(0,1)$	$CN(p,a)$	$C\chi^2(p,a)$	$C\text{Slash}(p)$
		50	s_{bar/c_4}	1.00017	1.16009	1.33454	3.89222	1.00017	1.30756
		<u>0.01845</u>	0.16009	0.33455	2.89223	<u>0.01845</u>	0.30755	0.63409	6.74117
	Q	1.00056	1.06451	1.05544	1.04824	1.00056	1.13353	1.11381	1.09947
		0.02236	0.06495	0.05635	0.04972	0.02236	0.13353	0.11382	0.09948
	S_c	1.00012	1.04515	1.02938	1.02735	1.00012	1.09751	1.06343	1.05764
		0.02009	0.04646	0.03320	0.03170	0.02009	0.09753	0.06376	0.05812
	S_{box}	1.00017	1.03585	1.02320	1.02195	1.00017	1.07801	1.05129	1.04661
		0.02282	0.03979	0.03087	0.03012	0.02282	0.07828	0.05281	0.04856
	S_n	0.99810	1.05077	1.04236	1.03696	0.99810	1.10828	1.08983	1.07892
		0.02512	0.05278	0.04574	0.04150	0.02512	0.10831	0.08998	0.07923
	MAD	1.00018	1.04320	1.03600	1.03179	1.00018	1.09030	1.07571	1.06576
		0.02952	0.04838	0.04324	0.04051	0.02952	0.09067	0.07661	0.06733
100	s_{bar/c_4}	1.00011	1.16021	1.33435	3.25007	1.00011	1.30778	1.63355	6.77074
		<u>0.01305</u>	0.16020	0.33435	2.25008	<u>0.01305</u>	0.30778	0.63355	5.77073
	Q	1.00051	1.06470	1.05530	1.04853	1.00051	1.13371	1.11355	1.09966
		0.01574	0.06473	0.05538	0.04870	0.01574	0.13370	0.11355	0.09966
	S_c	1.00005	1.04531	1.02924	1.02763	1.00005	1.09758	1.06315	1.05785
		0.01417	0.04547	0.03031	0.02887	0.01417	0.09758	0.06315	0.05788
	S_{box}	1.00009	1.03605	1.02310	1.02215	1.00009	1.07818	1.05100	1.04673
		0.01608	0.03701	0.02611	0.02543	0.01608	0.07820	0.05120	0.04701
	S_n	0.99805	1.05100	1.04215	1.03719	0.99805	1.10849	1.08948	1.07904
		0.01777	0.05129	0.04289	0.03836	0.01777	0.10849	0.08948	0.07905
	MAD	0.99948	1.04274	1.03513	1.03130	0.99948	1.08980	1.07459	1.06528
		0.02089	0.04412	0.03763	0.03460	0.02089	0.08981	0.07465	0.06545
200	s_{bar/c_4}	1.00014	1.16014	1.33401	5.61484	1.00014	1.30772	1.63318	6.65260
		<u>0.00925</u>	0.16013	0.33401	4.61482	<u>0.00925</u>	0.30771	0.63318	5.65257
	Q	1.00052	1.06456	1.05532	1.04847	1.00052	1.13360	1.11364	1.09969
		0.01117	0.06455	0.05532	0.04847	0.01117	0.13360	0.11363	0.09969
	S_c	1.00010	1.04516	1.02924	1.02751	1.00010	1.09745	1.06319	1.05788
		0.01005	0.04516	0.02939	0.02772	0.01005	0.09745	0.06320	0.05787
	S_{box}	1.00012	1.03593	1.02306	1.02215	1.00012	1.07814	1.05111	1.04671
		0.01140	0.03603	0.02390	0.02310	0.01140	0.07814	0.05112	0.04672
	S_n	0.99806	1.05086	1.04216	1.03719	0.99806	1.10837	1.08959	1.07906
		0.01259	0.05087	0.04223	0.03735	0.01259	0.10838	0.08959	0.07907
	MAD	1.00013	1.04318	1.03576	1.03191	1.00013	1.09030	1.07537	1.06596
		0.01475	0.04334	0.03623	0.03268	0.01475	0.09030	0.07538	0.06596

PERFORMANCE OF CONTROL CHARTS WITH ROBUST PROBABILITY LIMITS

The average run length (*ARL*) is commonly used as a summary measure in evaluating the performance of control charts. In practice, we require a large in-control *ARL* value that corresponds to a small false alarm rate, and a small out-of-control *ARL* value to enable rapid detection of undesirable increase in process variability. Let *E* denotes the event that a sample statistic *w* falls either above its estimated upper probability limit $U\hat{C}L_w$ or below its estimated lower probability limit $L\hat{C}L_w$. Let RL_k denotes

$$P_k(E | \hat{\sigma}) = 1 + F_W [(n - 1)B_{\alpha/2;n}^2 u^2 / k^2] - F_W [(n - 1)B_{1-\alpha/2;n}^2 u^2 / k^2]$$

where $F_W(\cdot)$ is the cumulative distribution function (*CDF*) of $W = (n-1)S^2 / \sigma^2$, and *u* is the value of $U = \hat{\sigma} / \sigma$.

In evaluating the performance of the *R*-chart we have

$$P_k(E | \hat{\sigma}) = 1 + F_W [D_{\alpha/2;n} u / k] - F_W [D_{1-\alpha/2;n} u / k]$$

where $W = R / \sigma$.

Our simulation study indicates that in the event that the preliminary samples are contaminated, the \bar{x} , *R* and *s* charts constructed with robust probability limits outperform those constructed with the classical non-resistance scale estimator. To avoid lengthy discussions, we shall only report the performance of the *s*-chart with robust probability limits constructed from the Gaussian and contaminated Gaussian preliminary samples. As the sampling distribution of $U = \hat{\sigma} / \sigma$ cannot be obtained explicitly for the scale estimators considered in Section 3, the method of Monte Carlo simulation is used to evaluate the $ARL(k)$ from equation (5).

A three steps Monte Carlo method used in our simulation study of the *s*-chart is summarized as follow:

Step 1: Generate *m* preliminary samples from each of the $N(0,1)$, $CN(p,a)$, $C\chi^2(p,c)$ and $CSlash(p)$ distributions with presumed values of *p*, *a* and *c*.

the run length between occurrences of the events *E* when the process variation shifted from σ to $k\sigma$. Then, given $\hat{\sigma}$, the conditional distribution of RL_k follows a geometric distribution with parameter $P_k(E | \hat{\sigma})$ and the *ARL* required to detect a shift of σ to $k\sigma$ in the process variation is given by

$$ARL(k) = E(RL_k) = \int_0^\infty \frac{1}{P_k(E | \hat{\sigma})} f_U(u) du \quad (5)$$

In evaluating the performance of the *s*-chart we have:

Step 2: Estimate the process standard deviation σ using each of the six scale estimators considered in Section 3 from each set of *m* preliminary samples generated in Step 1, and subsequently evaluate the probability limits of the *s*-chart.

Step 3: Compute the $ARL(k)$ of the *s*-chart required to detect a shift of process standard deviation from σ to $k\sigma$ in future production process.

Previous studies based on the normality assumption [17, 18], and that under the non-normality assumption [5], reveal that the number of preliminary samples used in estimating the location and scale parameters and subsequently the control limits of the control charts should be much greater than the usually suggested number of 20 to 30, especially when the sample size is small. Consequently 200 samples are used in our simulation study to obtain a reliable estimate of the unknown scale parameter. The entries of Tables 5 and 6 are evaluated using the sample mean Monte Carlo integration technique with 100,000 replications of $m = 200$ preliminary samples of size *n*. The estimates of S_c are computed from (3) with $c = 7$. The estimates of S_{box} are computed from (4) with $k_l = k_u = 2.563$ ($k_l = k_u = 2.239$) which correspond to the probability of $\alpha_0 = 0.05$ that one or more observations in a Gaussian sample of size $n = 10$ ($n = 20$) will be wrongly classified as outliers [10].

Table 5. The $ARL(k)$ values of the s -chart with robust and resistant probability limits constructed based on 200 preliminary samples, each of size n taken from the $CSlash(p)$ distribution. Note that $p=0$ corresponds to uncontaminated $N(0,1)$ preliminary samples. The $ARL(k)$ values required to detect shifts of process standard deviation from σ to $k\sigma$, $k=1.0(2)2.0$, are computed from equation (4) by generating 100,000 replications of $m=200$ preliminary samples. The underlined values are the smallest $ARL(k>I)$ values amongst the estimators considered

P	SCALE ESTIMA-TOR	$N(0, k^2), n=10$										$N(0, k^3), n=20$																																																																																																																																																																																																														
		$k=1.0$	$k=1.2$	$k=1.4$	$k=1.6$	$k=1.8$	$k=2.0$	$k=1.0$	$k=1.2$	$k=1.4$	$k=1.6$	$k=1.8$	$k=2.0$	$k=1.0$	$k=1.2$	$k=1.4$	$k=1.6$	$k=1.8$	$k=2.0$																																																																																																																																																																																																							
0.00	$sbar/c_4$	363.2368	<u>37.8087</u>	<u>7.8538</u>	<u>3.2935</u>	<u>2.0137</u>	<u>1.5162</u>	362.7415	<u>18.5699</u>	<u>3.4644</u>	<u>1.6517</u>	359.1402	18.6770	3.4701	1.6526	361.1422	18.5927	3.4647	1.6517	1.2113	1.0724	358.9010	18.6967	3.4714	1.6529	1.2116	1.0725	356.9569	18.7020	3.3109	2.0192	1.5185	354.4469	18.7943	3.4775	1.6540	1.2120	1.0727	205.2956	199.0878	86.2720	43.3979	26.0717	17.8867	390.4491	49.8907	9.3731	3.6850	2.1643	1.5885	380.1821	46.1023	9.4086	3.8594	2.2984	1.6815	383.0739	<u>44.5854</u>	<u>8.7227</u>	<u>3.5205</u>	<u>2.1018</u>	<u>1.5587</u>	383.3280	47.9023	9.1135	3.6163	2.1375	1.5755	376.8555	46.6835	8.9469	3.5707	2.1194	1.5667	47.3016	145.5351	174.8892	131.9559	91.1070	63.7707	393.4073	76.2231	12.4343	4.4247	2.4386	1.7176	392.4145	61.6531	12.1192	4.8480	2.8083	2.0098	399.7634	<u>58.0074</u>	<u>10.3789</u>	<u>3.9365</u>	<u>2.2606</u>	<u>1.6373</u>	395.4308	67.3680	11.4212	4.1835	2.3500	1.6761	392.7213	62.0328	10.7907	4.0289	2.2921	1.6488	6.8023	21.4686	59.3729	109.8867	136.4888	134.8130	314.8800	158.4616	21.3347	6.3105	3.0847	2.0085	369.0997	100.3950	18.8346	7.0187	3.7951	2.5640	376.7516	<u>95.6481</u>	<u>14.7977</u>	<u>5.0189</u>	<u>2.5681</u>	<u>1.8265</u>	349.4499	122.3037	17.4177	5.5124	2.8181	1.8902	368.7002	102.4379	15.2769	5.0522	2.6590	1.8183	4.3395	26.5947	85.9969	108.3880	93.1436	71.4968	337.3242	39.4657	5.1848	2.0240	1.3327	1.1181	375.4328	28.2195	4.3397	1.8471	1.2752	1.0964	376.7910	<u>26.0989</u>	<u>4.1405</u>	<u>1.8041</u>	<u>1.2616</u>	<u>1.0913</u>	354.3626	34.5000	4.8088	1.9461	1.3076	1.1086	361.9599	31.1213	4.5357	1.8876	1.2886	1.1015	1.0870	1.5751	3.8837	13.2797	35.2312	61.3120	206.0849	94.5852	8.5847	2.6461	1.5240	1.1905	313.1811	46.1713	5.6869	2.1311	1.3681	1.1350	340.1191	<u>38.6886</u>	<u>5.1263</u>	<u>2.0119</u>	<u>1.3288</u>	<u>1.1166</u>	250.1110	69.9104	7.1576	2.3974	1.4491	1.1622	290.2133	54.5494	6.1899	2.2176	1.3934	1.1411

Table 6. The $ARL_i(k)$ values of s-chart with resistant probability limits constructed based on 200 preliminary samples, each of size $n=20$, taken from the $CN(p, a)$ or $C\chi^2(p, c)$ distribution with $p=0.05$. The $ARL_i(k)$ values required to detect shifts of process standard deviation from σ to $k\sigma$, $k=1.0(0.2)2.0$, are computed from equation (4) by generating 100,000 replications of $m=200$ preliminary samples. The underlined values are the smallest $ARL_i(k>1)$ values amongst the estimators considered

a	ESTIMATOR	$CN(p=0.05, a)$							$C\chi^2(p=0.05, c)$						
		SCALE							SCALE						
		$N(\theta, k^2)$							$N(\theta, k^2)$						
		$k=1.0$	$k=1.2$	$k=1.4$	$k=1.6$	$k=1.8$	$k=2.0$	$k=1.0$	$k=1.2$	$k=1.4$	$k=1.6$	$k=1.8$	$k=2.0$		
1.0	sbar/c ₄	362.6897	<u>18.5556</u>	<u>3.4630</u>	<u>1.6515</u>	<u>1.2112</u>	<u>1.0724</u>	362.6897	<u>18.5556</u>	<u>3.4630</u>	<u>1.6515</u>	<u>1.2112</u>	<u>1.0724</u>		
	Q	360.0271	18.7984	3.4818	1.6554	1.2125	1.0728	360.0271	18.7984	3.4818	1.6554	1.2125	1.0728		
	S _c	360.9516	18.5739	3.4629	1.6512	1.2111	1.0723	360.9516	18.5739	3.4629	1.6512	1.2111	1.0723		
	S _{box}	358.3636	18.6755	3.4691	1.6523	1.2115	1.0725	358.3636	18.6755	3.4691	1.6523	1.2115	1.0725		
	S _n	352.1063	18.2543	3.4248	1.6416	1.2079	1.0711	352.1063	18.2543	3.4248	1.6416	1.2079	1.0711		
	MAD	351.8577	19.0521	3.4946	1.6571	1.2130	1.0731	351.8577	19.0521	3.4946	1.6571	1.2130	1.0731		
2.0	sbar/c ₄	286.1798	54.3781	6.2119	2.2257	1.3964	1.1422	86.5691	301.9073	25.4487	4.8198	2.0955	1.3985		
	Q	352.7652	35.2110	4.8713	1.9600	1.3122	1.1104	346.3140	36.9910	5.0038	1.9872	1.3209	1.1137		
	S _c	364.8808	31.9087	4.6209	1.9081	1.2955	1.1040	376.1107	27.8883	4.2957	1.8385	1.2729	1.0955		
	S _{box}	370.2440	<u>29.6031</u>	<u>4.4310</u>	<u>1.8671</u>	<u>1.2822</u>	<u>1.0990</u>	376.9078	<u>25.9013</u>	<u>4.1237</u>	<u>1.8004</u>	<u>1.2604</u>	<u>1.0908</u>		
	S _n	364.4395	31.2965	4.5618	1.8945	1.2910	1.1023	363.5330	31.5613	4.5818	1.8986	1.2923	1.1028		
	MAD	363.8640	30.4040	4.4798	1.8759	1.2848	1.1000	364.8950	29.8692	4.4365	1.8666	1.2818	1.0989		
3.0	sbar/c ₄	106.2112	248.7849	17.5444	3.9387	1.8820	1.3231	23.3427	193.4881	203.1537	23.3687	5.2032	2.3233		
	Q	293.9124	52.2071	6.0621	2.1962	1.3871	1.1387	318.8216	44.6344	5.5508	2.0970	1.3559	1.1269		
	S _c	344.4789	37.5319	5.0481	1.9967	1.3240	1.1148	373.3660	29.0194	4.3878	1.8583	1.2793	1.0979		
	S _{box}	361.4250	<u>32.5444</u>	<u>4.6631</u>	<u>1.9162</u>	<u>1.2981</u>	<u>1.1050</u>	376.2624	<u>26.4923</u>	<u>4.1736</u>	<u>1.8114</u>	<u>1.2640</u>	<u>1.0921</u>		
	S _n	328.9562	41.8488	5.3481	2.0559	1.3428	1.1219	348.5014	36.2257	4.9390	1.9730	1.3163	1.1119		
	MAD	343.7064	37.4180	5.0151	1.9872	1.3207	1.1136	356.8591	33.0864	4.6894	1.9200	1.2991	1.1054		

Table 5 reveals that when the preliminary samples are uncontaminated (corresponds to $p=0$), then as expected the probability limits of the s -chart constructed with the classical scale estimator \bar{s}/c_4 yields in-control $ARL(k=1)$ value closest to the target value 370.37 and has the smallest out-of-control $ARL(k>1)$ values. However, when the preliminary samples data are contaminated with the long-tailed $CSlash(p)$ distribution with $p=0.02, 0.05, 0.10$, the s -chart constructed with the estimator \bar{s}/c_4 not only leads to out-of-control $ARL(k>1)$ values larger than that constructed with the robust estimators but its in-control $ARL(k=1)$ values are also unacceptably small. For instance, when preliminary samples of size $n=20$ are taken from the $CSlash(p)$ distribution with $p=0.10$, the s -chart constructed with the estimator \bar{s}/c_4 yields in-control $ARL(k=1)$ value of 1.087 which is equivalent to a high false alarm rate of 92%. This is due to the fact that the sampling distribution of the sample standard deviation S is highly skewed to the right, thus even a small to moderate over-estimate of σ would result in its lower probability limit cuts off more than the intended 0.135% area in the fat left tail of the distribution of S and consequently leads to higher false alarm rate. In contrast, a s -chart constructed with the robust scale estimators not only leads to smaller $ARL(k>1)$ values but also has the required large $ARL(k=1)$ values.

Table 5 also clearly reveals that the probability limits of the s -chart constructed using the robust estimator S_{box} yields the best $ARL(k=1)$ and the smallest $ARL(k>1)$ values amongst the estimators considered. For example, when preliminary samples of size $n=20$ are taken from the $CSlash(p)$ distribution with $p=0.10$, the s -chart constructed with the estimator S_{box} not only yields the smallest out-of-control $ARL(k>1)$ values but also provide the smallest false alarm rate as it has the largest in-control $ARL(k=1)$ value of 340.12 amongst the estimators considered.

Examination of Table 6 reveals that the s -chart constructed with S_{box} yields the smallest out-of-control $ARL(k>1)$ values when preliminary samples of size $n=20$ are taken from the

contaminated $CN(p,a)$ and $C\chi^2(p,c)$ distributions with $p=0.05$. Note that $a=1$ and $c=0$ correspond to the case when the preliminary samples are uncontaminated and are taken from the standard Gaussian distribution.

REMARKS

The proposed control chart with robust probability limits is constructed by assuming that the underlying distribution of the quality characteristic is known and its scale parameter is estimated using resistant estimators. Our simulation study indicates that \bar{x} , R and s charts constructed with robust probability limits outperform the classical Shewhart chart when the preliminary samples are drawn from a contaminated Gaussian distribution. However, to avoid lengthy discussions, we only report the performance of the s -chart constructed with robust probability limits. The s -chart constructed with its probability limits evaluated using the estimator S_{box} yields the best in-control ARL and the smallest out-of-control ARL values amongst the robust and resistant estimators considered. Our results obtained from this study also reveal that the proposed estimator S_{box} is the most efficient and resistant estimator of scale amongst the estimators and contaminated distributions considered.

It cannot be denied that the robust estimation of the location and scale parameters is computation intensive and therefore clearly excludes the use of a hand-held calculator. However, this should not be an issue at this modern age where computing facilities are readily available and accessible at low cost.

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